

# Scanning Probe Lithography Patterning of Monolayer Semiconductors and Application in Quantifying Edge Recombination

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Scanning probe lithography is used to directly pattern monolayer transition metal dichalcogenides (TMDs) without the use of a sacrificial resist. Using an atomic-force microscope, a negatively biased tip is brought close to the TMD surface. By inducing a water bridge between the tip and the TMD surface, controllable oxidation is achieved at the sub-100 nm resolution. The oxidized flake is then submerged into water for selective oxide removal which leads to controllable patterning. In addition, by changing the oxidation time, thickness tunable patterning of multilayer TMDs is demonstrated. This resist-less process results in exposed edges, overcoming a barrier in traditional resist-based lithography and dry etch where polymeric byproduct layers are often formed at the edges. By patterning monolayers into geometric patterns of different dimensions and measuring the effective carrier lifetime, the non-radiative recombination velocity due to edge defects is extracted. Using this patterning technique, it is shown that selenide TMDs exhibit lower edge recombination velocity as compared to sulfide TMDs. The utility of scanning probe lithography towards understanding material-dependent edge recombination losses without significantly normalizing edge behaviors due to heavy defect generation, while allowing for eventual exploration of edge passivation schemes is highlighted, which is of profound interest for nanoscale electronics and optoelectronics.

2D monolayer transition metal dichalcogenides (TMDs) possess a variety of unique properties applicable toward different optical and electronic applications.<sup>[1–4]</sup> Uniquely, the monolayers exhibit self-terminated surfaces without dangling bonds, limiting the number of defects that can exist. However, in contrast to the surface, the edges are filled with dangling bonds which

could lead to detrimental effects on device performance.<sup>[5–9]</sup> For the development of practical 2D nanoelectronics and optoelectronics, the 2D semiconductor is required to be etched to proper nanoscale patterns. This means the formation of edges is inevitable. Moreover, the edge-to-surface ratio will increase with further pattern scaling, causing the problems associated with these edges to become more severe. In that respect, edge effects are important to be quantified and controlled by developing proper etching and passivation schemes. Yet to this day, this remains a largely unexplored research topic. Recently, we introduced a metric to ascertain the edge quality of monolayer TMDs called edge recombination velocity (ERV). Briefly, TMD monolayers are patterned into lateral dimensions where most excitons travel to the edge sites for recombination due to diffusion. ERV is then extracted by measuring the lifetime of monolayer TMDs as a function of patterned dimensions using time-resolved photoluminescence (TRPL).<sup>[10]</sup> The ideal edge patterning

technique should not significantly impact the edge properties of different TMDs during the fabrication process. Specifically, the traditionally explored resist-based lithography and plasma dry etching processes often leave a polymeric byproduct layer at the patterned edges, which limits study of the intrinsic edge properties. The mitigation of fabrication-induced defects will allow us to understand intrinsic material dependent edge property variations instead. One promising technique to overcome this problem is scanning probe lithography (SPL),<sup>[11,12]</sup> where surface patterning is conducted by applying a voltage between a probe tip and the substrate without the use of a sacrificial resist.

In this work, we utilize SPL to pattern monolayers of MoS<sub>2</sub>, MoSe<sub>2</sub>, WS<sub>2</sub>, and WSe<sub>2</sub> on SiO<sub>2</sub>/Si substrates while investigating the various parameters that can affect the patterning process. These parameters include tip bias, dwell time, humidity, and setpoint amplitude. By fine tuning these parameters, we demonstrate a patterning resolution of <100 nm and a thickness dependent oxidation of thicker TMDs through variation of tip dwell time. To ascertain the edge quality of monolayer TMDs, edge recombination velocity

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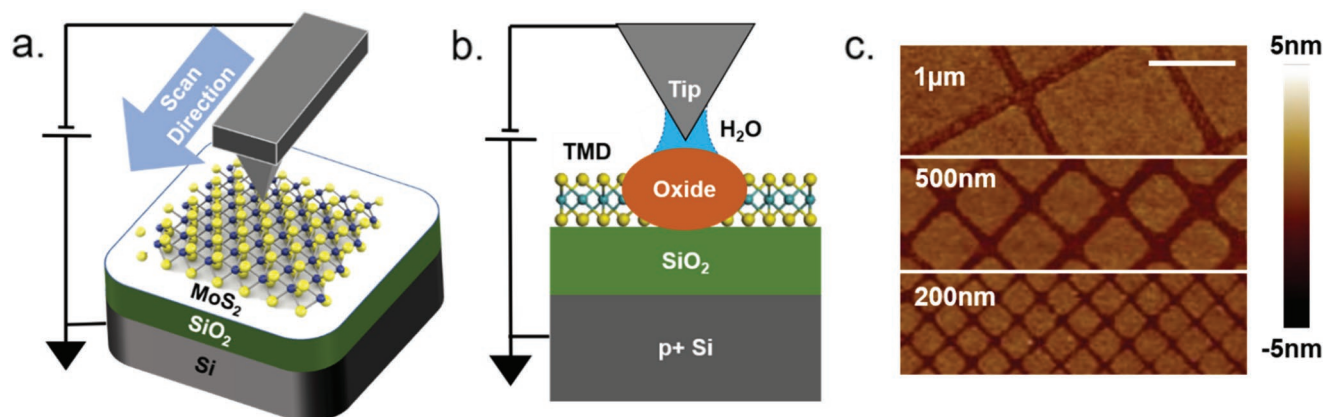
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**Figure 1.** a) A representative schematic of the SPL patterning of a MoS<sub>2</sub> monolayer. b) The sideview illustration, depicts the formation of a water bridge between the tip and the monolayer as a bias is applied, leading to the local oxidation of the monolayer. c) AFM images of a MoS<sub>2</sub> monolayer patterned into grids of different dimension after water removal of the MO<sub>x</sub> patterned area. Scale bar represents 500 nm.

(ERV) – a metric that we have previously introduced – is utilized.<sup>[10]</sup> In this study, we extract ERVs of four TMDs (MoS<sub>2</sub>, MoSe<sub>2</sub>, WS<sub>2</sub>, and WSe<sub>2</sub>) patterned via SPL. Compared to the extracted ERV of WS<sub>2</sub> fabricated with e-beam lithography in a previous study, we observe lower ERV and higher edge lifetime ( $\tau_{\text{edge}}$ ). In addition, the selenides are found to exhibit lower ERVs compared to sulfides. We also show that it is possible to passivate the edges by chemical treatment as the edges formed by SPL are exposed without any residual coating.

Figure 1a,b illustrates the SPL for patterning monolayer TMDs (preparation of TMD materials is shown in the Supporting Information) via atomic force microscope (AFM). During lithography, a diamond-like-carbon (DLC) coated silicon tip (Bruker, DDESP-V2) was brought close to the surface (with an amplitude setpoint of  $\approx 0.6$  nm) while a voltage was applied across from the tip ( $V_{\text{tip}} = -12$  V) to the Si substrate ( $V_{\text{sub}} = 10$  V). Precise tip movements during SPL are captured via AFM's high speed data capture card and are included in Figure S1 in the Supporting Information. The AFM chamber was also maintained at  $<25\%$  humidity. After oxidation, the entire flake was submerged in DI water, where the oxidized region was selectively removed while leaving the rest of the flake intact. Figure 1c shows a MoS<sub>2</sub> monolayer patterned into grids of three different sizes – 1  $\mu\text{m}$ , 500 nm, and 250 nm respectively – using SPL. Notably, the monolayers are patterned on a SiO<sub>2</sub>/Si substrate rather than on a conductive substrate, where the voltage was capacitively coupled through the insulating substrate. The use of a SiO<sub>2</sub>/Si substrate provides a more practical platform for optoelectronic characterization and device applications.

SPL lithography consists of two parts – TMD oxidation and selective oxide removal via water. To enable oxidation, a water bridge first forms between the AFM tip and the TMD surface via a voltage application at the AFM tip. The oxidation reaction proceeds as:<sup>[11,13–15]</sup>



where M stands for the transition metal of interest, and X the chalcogen of interest.  $x$  and  $y$  take on different values depending on the specific TMD in question. After oxidation,

the sub-stoichiometric transition metal oxides can be removed via water as reported elsewhere.<sup>[11,16]</sup>

To elucidate the oxidation mechanism, focus was on appropriate conditions when water bridge formation was favorable. The resultant oxidation area (or SPL resolution) was directly related to the water bridge coverage area over the TMD surface. While the details of the water bridge formation is described elsewhere,<sup>[17]</sup> it was qualitatively related that the key experimental parameters with known model to establish consistency.

Generally, water bridge formation was favorable when the following energy relation is satisfied

$$\Delta U = U(\text{water bridge}) - U_o(\text{vapor}) = \Delta U_s + \Delta U_c + \Delta U_{\text{vdw}} + \Delta U_e < 0 \quad (2)$$

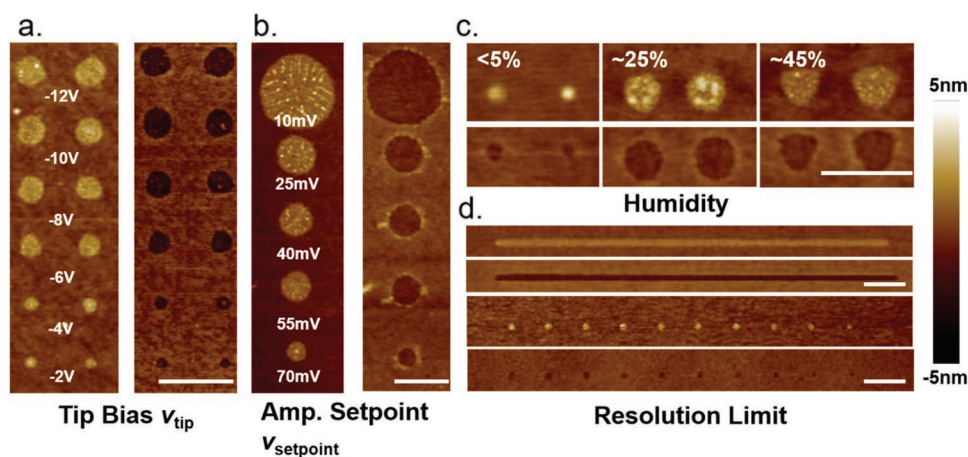
where

$$\Delta U_e(V_{\text{tip}}), \Delta U_c(RH), \Delta U_{\text{vdw}}(V_{\text{setpoint}}) \quad (3)$$

The potential energy difference,  $\Delta U$ , shows a competitive process between water condensation and water vapor formation. To determine whether a bridge forms, the surface energy ( $U_s$ ), condensation energy ( $U_c$ ), van der Waals energy ( $U_{\text{vdw}}$ ), and electrostatic energy ( $U_e$ ) of the system was summed together. When  $\Delta U < 0$ , the water bridge forms. As  $\Delta U$  becomes more negative (or more favorable for water bridge formation), the water bridge also increases in width, resulting in a larger TMD surface coverage, larger oxidized area and lower SPL resolution. It was expected increasing tip bias  $V_{\text{tip}}$  (increasing  $\Delta U_e$ ), decreasing tip to surface distance (increasing  $\Delta U_{\text{vdw}}$ ) and increasing humidity (decreasing  $\Delta U_c$ ) to all contribute to a more stable, and wider water bridge formation.

The impacts of the mentioned parameters are shown in Figure 2. Figure 2a shows the impact of tip bias  $V_{\text{tip}}$  on the oxidation process. When  $V_{\text{tip}}$  changes from  $-12$  to  $-2$  V, the oxidized area becomes smaller, implying a smaller water bridge with reduced  $V_{\text{tip}}$ . This is expected as  $V_{\text{tip}}$  affects the water bridge formation via<sup>[17]</sup>

$$U_e = \frac{\epsilon_0}{2} \int_V \epsilon |E|^2 dV \quad (4)$$



**Figure 2.** Effects of changing SPL process parameters on the patterning resolution of TMD monolayers. a) Tip voltage bias variation; higher tip voltage corresponds to a larger oxidation area (left panel) and subsequently a larger patterned area after oxide removal by water (right panel). b) Amplitude setpoint variation; the closer the tip approaches the surface, the larger the oxidized spot (left panel) and the correspondingly larger patterned area after oxide removal (right panel). c) Humidity variation; adequate oxidation dot size requires a high enough humidity, where above the threshold humidity level, beyond which no significant variation in oxidation size exists. d) Finest resolution limit achievable via SPL, showing both dots and lines at <100 nm resolution respectively by tuning all parameters. For all the dots/circles, the tip is held at a constant position on the monolayer. For the lines, the tip is scanned along a single axis. Scale bar is 500 nm.

Here  $\epsilon_0$  is the vacuum permittivity,  $E$  is the space-varying (or tip-induced) electric field,  $\epsilon$  is the relative permittivity of the relevant liquid (water), and  $V$  is the volume of the condensed liquid. Figure S4 in the Supporting Information illustrates approximate shape of the meniscus before water bridge formation and the relevant integral volume. It can be seen that at a smaller  $V_{\text{bias}}$ , the electric field  $E$  between the tip and TMD surface is smaller, leading to a smaller  $U_c$ . From Equation (2) we see that a smaller  $\Delta U_c$  (when a tip bias is applied versus when a tip bias is not applied) minimizes  $|\Delta U|$ , correlated to a smaller water bridge formation and consistent with Figure 2a.

Next, the impact of amplitude setpoint,  $V_{\text{setpoint}}$ , on oxidation is investigated.  $V_{\text{setpoint}}$  is the feedback parameter that AFM attempts to maintain during SPL and is related to the tip-to-TMD surface vdW force. The voltage value refers to the tip amplitude oscillation at a fixed drive amplitude of the piezo element, with a smaller oscillation achieved by tip lowering to maintain surface tracking. Changing the voltage setpoint directly decreases or increases the distance of the tip to TMD surface and changes the vdW force experienced between the two interfaces. The vdW force between water molecules can be described via the following relation<sup>[17]</sup>

$$U_{\text{vdw}} = \frac{H}{12\pi} \int_s \frac{1}{\xi^2} ds \quad (5)$$

where  $H$  is the Hamaker constant,  $S$  is the surface area of the TMD/water interface, and  $\xi$  is a distance between the top and bottom surfaces of the water bridge. We see in Equation (5) that the tip-surface distance enters into the vdW energy calculation via  $\xi$ , where a larger separation translates to a smaller  $U_{\text{vdw}}$  and vice versa. Therefore, we expect that a lower setpoint during lithography will lead to a larger oxidized area (due to a more stable and larger water bridge) while a higher setpoint leads to a smaller oxidized area. Figure 2b confirms this expectation

as we change the tip-to-surface distance from 0.63 to 4.4 nm (directly corresponding to the appropriate  $V_{\text{setpoint}}$ ).

Lastly, relative humidity, RH, is defined as the ratio between water vapor concentration in the air normalized to the saturation concentration of water vapor. RH influences the oxidation process by controlling the condensation energy ( $U_c$ ) where the following relation applies<sup>[17]</sup>

$$U_c = \frac{R_g T}{v_m} \ln\left(\frac{1}{\text{RH}}\right) \int_v dv \quad (6)$$

where  $R_g$  is the gas constant,  $T$  is the temperature, and  $v_m$  is the molar volume of liquid. The condensation energy is also evaluated over the volume of the condensed liquid  $V$  present similar to Equation (4) and illustrated in Figure S4 in the Supporting Information. Note that the above relation only holds for water vapor before supersaturation; for condensation of other liquids, RH becomes a ratio of vapor pressure at the condition of interest divided by vapor pressure at saturation.

From Equation (6), it was expected very limited oxidation (therefore very small water bridge formation) would occur at lower humidity. Lower RH translates into a higher  $U_c$ , implying difficulty in liquid condensation and easier vapor formation. Qualitatively, lower RH means a drier environment, which drives water vapor formation over condensation. As  $U_c$  increases,  $\Delta U$  from Equation (2) becomes more positive, translating to a smaller water bridge coverage. Conversely, water bridge width should increase at higher RH, leading to an increased oxidation area. Interestingly, continuous incremental increase in RH results in a slower incremental increase of the oxidation area due to the natural log function. Figure 2c substantiates this hypothesis and demonstrates a significant difference in the oxidation area as RH changes from <5% to 25%, and a much smaller difference (if any) in oxidation size between 25% to 45% humidity.

After examining the water bridge formation mechanism, it was discussed the oxidation process.  $V_{\text{tip}}$  can be either positive

or negative (with respect to the TMD surface) for a successful water bridge formation.<sup>[17]</sup> However, negative  $V_{\text{tip}}$  is needed to induce the oxidation reaction. While some TMDs ( $\text{MoS}_2$ ,  $\text{MoSe}_2$ ,  $\text{WS}_2$ , and  $\text{WSe}_2$  being the relevant TMD members) spontaneously oxidize under ambient conditions (at a very slow rate),<sup>13,14</sup> it was postulated that the negative tip bias supplies a larger amount of  $\text{OH}^-$  from the water bridge to the TMD surface, speeding up the general reaction detailed in Equation (1). Furthermore, the Fermi level of the TMD is moved by the applied voltage which further reduces the oxidation energy.

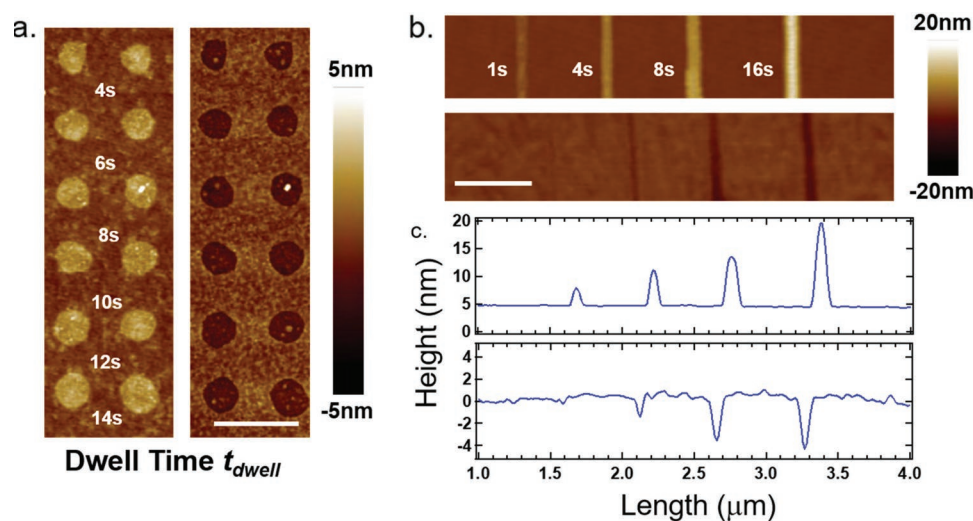
Finally, by optimizing the various parameters discussed above, the smallest dimension of dots and lines achievable via SPL are demonstrated in Figure 2d. Both the line width and the dot diameters are  $<100$  nm. The condition is set at  $V_{\text{tip}} = -2$  V (with a substrate bias of 10 V),  $V_{\text{setpoint}} = 30$  mV, and  $\text{RH} \approx 35\%$ . Any further efforts at reducing the SPL resolution leads to inconsistencies in the line patterning. Smaller dimension has been reported via SPL on TMDs elsewhere, and we attribute other factors (such as tip radius, tip type, and differences in the surface energies  $\Delta U_s$ ) to also play a role in reaching the highest resolution possible.<sup>[11]</sup>

In tuning various SPL parameters for oxidation, we found an interesting effect of oxidation dwell time  $t_{\text{dwell}}$  related to multilayer TMDs. While the impact of  $t_{\text{dwell}}$  is not explicitly included in Equation (2), longer  $t_{\text{dwell}}$  should give more time for oxidation to complete at a specific water bridge size. While the impact of  $t_{\text{dwell}}$  is harder to observe for monolayer TMDs (due to the relatively short time a monolayer can be completely oxidized), thicker TMDs need more time to fully oxidize. Therefore, a thickness dependent oxidation effect can be observed as it was scan  $t_{\text{dwell}}$ , specifically for thicker TMDs. **Figure 3** shows a time dependence of the oxidation process for both monolayers and multilayer TMDs.

For monolayers,  $t_{\text{dwell}}$  starts having negligible effects on the oxidation pattern after a slight increase in oxidized area going from 4–6 s. This is most likely because monolayer oxidation under the water bridge completes quickly ( $<4$  s), and vertical oxidation dependence is hard to observe at the monolayer thickness. Note that because  $t_{\text{dwell}}$  is not included in Equation (2), the size of the water bridge formed should be the same for all different  $t_{\text{dwell}}$  cases, leading to similarly sized monolayer oxidation. Figure 3b shows the same dwell time variation applied to thicker TMD layers. Here, a clear depth dependence is seen when  $t_{\text{dwell}}$  increases. Similar to SPL oxidation of silicon,<sup>[18,19]</sup> deeper layers of TMDs are oxidized at longer  $t_{\text{dwell}}$ , resulting in thicker oxides accompanied by a deeper trench after water submersion shown in Figure 3c. This oxidation depth dependence on  $t_{\text{dwell}}$  also highlights the potential of SPL used towards controllable layer-by-layer oxidation of thicker TMDs for various applications.

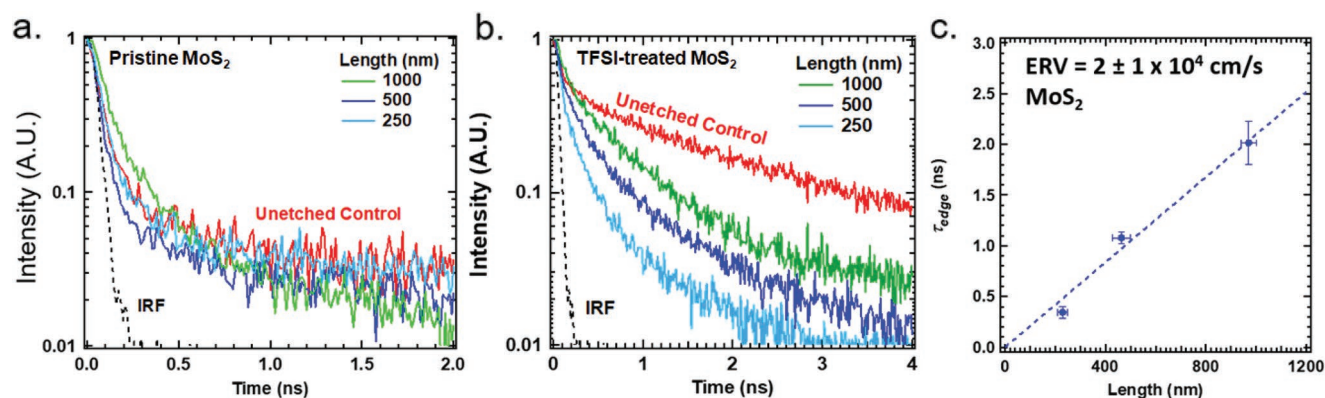
Compared to the more commonly used lithography techniques (such as photo- or e-beam lithography combined with wet or dry etching), SPL (combined with water removal) can avoid many nonidealities such as resist residues, electron backscattering effects, and etching-related contaminations.<sup>[20,21]</sup> Therefore, SPL was used to pattern monolayer  $\text{MoS}_2$ ,  $\text{MoSe}_2$ ,  $\text{WS}_2$ , and  $\text{WSe}_2$  TMDs in the same fashion shown in Figure 1c. We then measured their respective ERVs to assess their intrinsic edge qualities.

Briefly, all four TMDs are patterned down into square arrays with three different length  $l$  (1  $\mu\text{m}$ , 500 nm, and 250 nm). As  $l$  decreases, the increased circumference to surface area ratio means a higher contribution of the edge recombination effects, resulting in lower photoluminescence (PL) intensity after fill factor corrections (Figure S2, Supporting Information). Utilizing TRPL for lifetime measurements, we identify the lower



**Figure 3.** Dwell time effects on SPL patterning of monolayer and multilayer  $\text{MoS}_2$ . a) Dwell time effect on monolayer patterning, before (left panel) and after (right panel) water removal of the oxide. Dwell time has minimal effect on the oxidation area for the explored dwell time range. b) Dwell time effect on multilayer ( $<50$  nm in thickness) patterning. Increasing dwell time increases the oxidation depth. Four different  $t_{\text{dwell}}$  are used on a TMD multilayer, where each successive increase shows a thicker oxidation (top panel) and deeper trenches (bottom panel) after water removal of the oxide. c) AFM height scan of the TMD surface presented in b) after oxidation (top panel) and water removal of the oxide (bottom panel). Scale bar is 500 nm.





**Figure 4.** Edge recombination velocity extraction of MoS<sub>2</sub>. a) TRPL of MoS<sub>2</sub> squares of varying lengths of 250 nm, 500 nm, and 1  $\mu\text{m}$ , including an unetched control sample. b) TRPL of the same MoS<sub>2</sub> samples after TFSI treatment. c) Length dependence of  $\tau_{\text{edge}}$  for TFSI-treated MoS<sub>2</sub>, yielding an ERV  $\approx 2 \times 10^4 \text{ cm s}^{-1}$ .

carrier concentration regime (at  $\approx 10^{-1} \text{ W cm}^{-2}$  power density for all four TMDs) to extract the relevant effective lifetimes.<sup>[22,23]</sup> The effective lifetime ( $\tau_{\text{effective}}$ ) is broken down into a surface lifetime ( $\tau_{\text{surface}}$ ) and an edge lifetime ( $\tau_{\text{edge}}$ )

$$\frac{1}{\tau_{\text{effective}}} = \frac{1}{\tau_{\text{surface}}} + \frac{1}{\tau_{\text{edge}}} \quad (7)$$

The surface lifetimes are measured on unetched monolayers as 1.5, 10.9, 1.18, and 0.9 ns for MoS<sub>2</sub>, MoSe<sub>2</sub>, WS<sub>2</sub>, and WSe<sub>2</sub> respectively.  $\tau_{\text{edge}}$  is then extracted and correlated to ERV via Equation (8). Due to the square cross sections of the flake, the geometric correction factor relating ERV to  $\tau_{\text{edge}}$  derivation changes slightly as compared to the previously reported work using disks<sup>[10]</sup> with details included in supporting information

$$\tau_{\text{edge}} = \frac{l}{2 \times \text{ERV}} \quad (8)$$

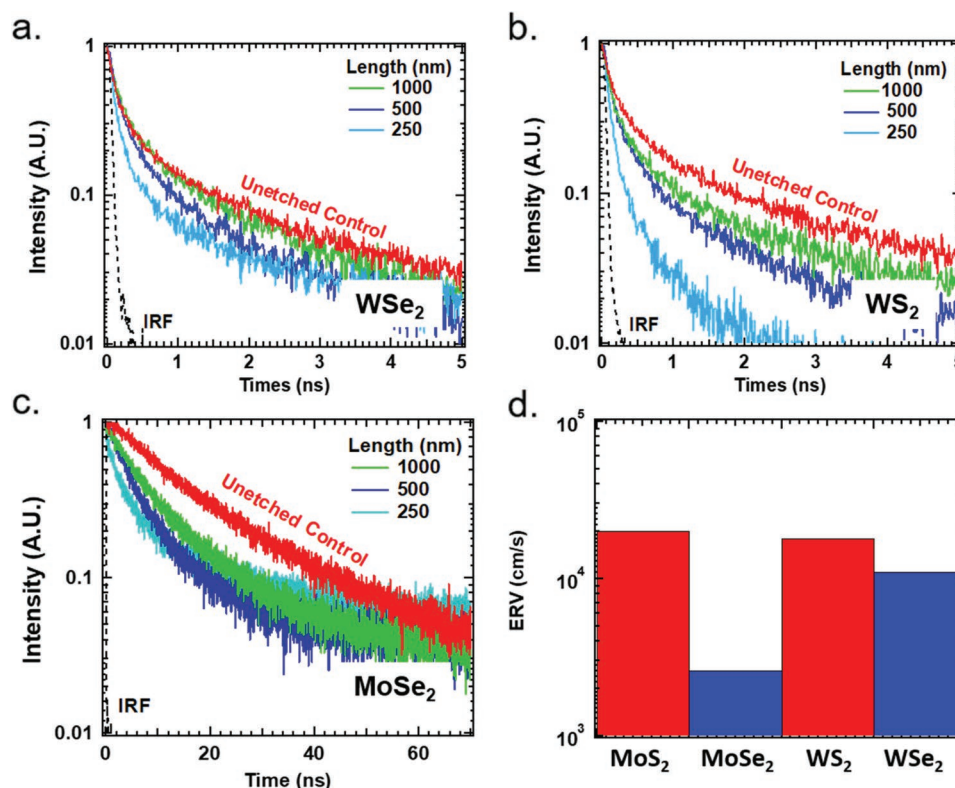
Extraction of MoS<sub>2</sub> ERV proves particularly challenging. **Figure 4a** shows the TRPL of MoS<sub>2</sub> for various sizes, including an unetched monolayer control. In addition to the lifetime being close to the instrument response function (which is remedied by employing iterative re-convolution), the unetched control  $\tau_{\text{effective}}$  is very close to that of the etched samples of all three sizes. This introduces a very large error in  $\tau_{\text{edge}}$  extraction using Equation (3). A more accurate extraction of  $\tau_{\text{edge}}$  therefore requires that  $\tau_{\text{surface}} \gg \tau_{\text{effective}}$ , or where length dependence is clearly observed from the TRPL series.

Since the entire SPL process only involves DI water removal after oxidation and does not use any polymeric based resist/organic chemicals, the resulting edges are free of polymeric byproducts often observed in dry etching processes. By employing a previously developed electron counter-doping scheme,  $\tau_{\text{surface}}$  of a SPL-patterned MoS<sub>2</sub> monolayer can be improved with bis(trifluoromethane) sulfonimide (TFSI).<sup>[22,23]</sup> **Figure 4b** shows the TRPL of the sample after TFSI treatment with the corresponding ERV shown in **Figure 4c**. In contrast, no lifetime change with chemical treatment is observed in samples patterned with standard resist-based lithography and plasma dry etching.<sup>[10]</sup>

**Figure 5a–c** shows the TRPL of WSe<sub>2</sub>, WS<sub>2</sub>, and MoSe<sub>2</sub> respectively, and the extracted ERVs of the four studied TMDs are shown in **Figure 5d**. Individual TMD steady state PL and ERV extractions are detailed in **Figure S2–S3** in the Supporting Information. The extracted ERVs are  $2 \times 10^4$ ,  $2.6 \times 10^3$ ,  $1.8 \times 10^4$ , and  $1.1 \times 10^4 \text{ cm/s}$  for MoS<sub>2</sub>, MoSe<sub>2</sub>, WS<sub>2</sub>, and WSe<sub>2</sub> respectively. From the previous work, WS<sub>2</sub> edges made with resist-based e-beam lithography has a measured ERV of  $4 \times 10^4 \text{ cm s}^{-1}$ . Compared to the SPL WS<sub>2</sub> ERV of  $1.8 \times 10^4 \text{ cm s}^{-1}$  measured here, it was observed a  $>2\times$  improvement with  $\tau_{\text{edge}}$  improving from 0.2–0.3 to 1.1 ns (**Figure S3d**, Supporting Information) at 500 nm length regime extracted via TRPL.<sup>[10]</sup> As expected, the ERV varies between different etching processes due to the different defect densities introduced by each process and potential passivation effect from resist residue.

Other works have shown TMD selenides to possess longer surface lifetime. Interestingly, MoSe<sub>2</sub> ERV is approximately an order smaller than the other three TMDs, and quite clearly mimics the material's surface properties. This ERV variation corresponds clearly to the much longer  $\tau_{\text{surface}}$  of MoSe<sub>2</sub> ( $\approx 116 \text{ ns}$ ) compared to the  $\tau_{\text{surface}}$  of the other three TMDs ( $\approx 3$ ,  $\approx 10$ , and  $\approx 20 \text{ ns}$  for WS<sub>2</sub>, MoS<sub>2</sub> with TFSI, and WSe<sub>2</sub> respectively).<sup>[24]</sup> This large ERV variation highlights the differences in edge properties as a function of the material rather than the etching process. Therefore, SPL demonstrates itself as an ideal lithography method for future ERV study due to the observable material dependent edge variations after patterning.

In conclusion, an in-depth investigation of the various parameters affecting SPL patterning of TMDs is discussed. Voltage bias, amplitude setpoint, and humidity have all shown tunability on TMD monolayer oxidation and are consistent with known theory, reaching sub-100 nm resolution. The oxidized area can be selectively removed via water to complete the lithography process. In addition, SPL dwell time can be used to control the thickness of oxidized multilayer TMDs, demonstrating the possibility of layer-by-layer oxidation control. Finally, SPL has been used to extract the ERV of four different TMD materials MoS<sub>2</sub>, MoSe<sub>2</sub>, WS<sub>2</sub>, and WSe<sub>2</sub>. Due to the lack of exposure to resist or plasma species, the process yields material dependent edges properties, reinforcing SPL as an attractive patterning



**Figure 5.** Time resolved photoluminescence measurements of SPL patterned squares of a) WSe<sub>2</sub>, b) WS<sub>2</sub> and c) MoSe<sub>2</sub>. d) Extracted edge recombination velocity for all four TMDs. Selenium based compounds are observed to have relatively lower ERVs compared to the sulfides.

technique for future edge passivation studies and comparative edge structure characterizations.

## Supporting Information

Supporting Information is available from the Wiley Online Library or from the author.

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## Conflict of Interest

The authors declare no conflict of interest.

## Keywords

2D materials, edge recombination velocity, scanning probe lithography

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# ADVANCED MATERIALS

## Supporting Information

for *Adv. Mater.*, DOI: 10.1002/adma.201900136

Scanning Probe Lithography Patterning of Monolayer  
Semiconductors and Application in Quantifying Edge  
Recombination

*Peida Zhao, Ruixuan Wang, Der-Hsien Lien, Yingbo Zhao,  
Hyungjin Kim, Joy Cho, Geun Ho Ahn, and Ali Javey\**



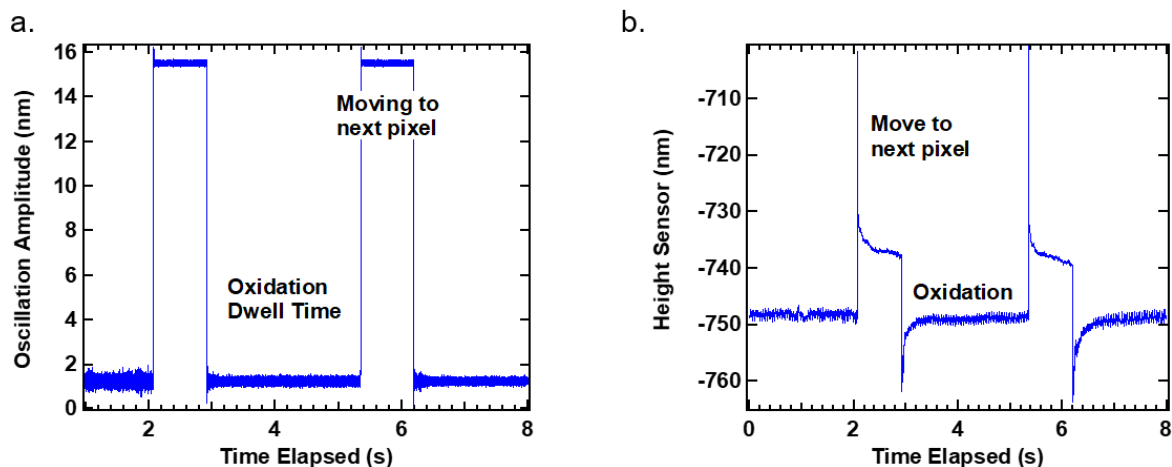
## Supporting Information

**Scanning Probe Lithography Patterning of Monolayer Semiconductors and Its Application for Quantifying Edge Recombination**

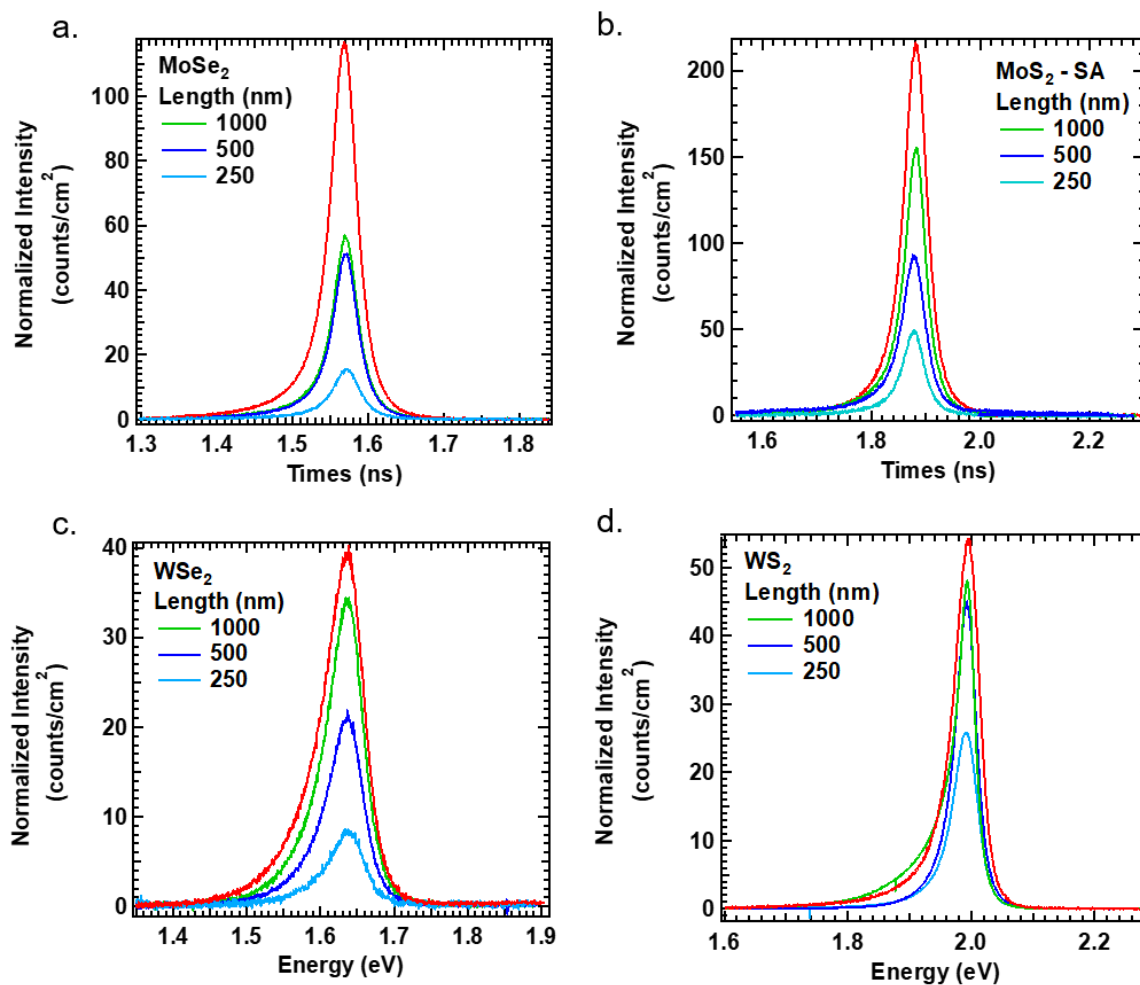
*Peida Zhao<sup>1,2</sup>, Ruixuan Wang<sup>1</sup>, Der-Hsien Lien<sup>1,2</sup>, Yingbo Zhao<sup>1,2</sup>, Hyungjin Kim<sup>1,2</sup>, Joy Cho<sup>1</sup>, Geun Ho Ahn<sup>1,2</sup>, and Ali Javey<sup>1,2\*</sup>*

<sup>1</sup> *Electrical Engineering and Computer Sciences, University of California at Berkeley, Berkeley, California 94720, United States*

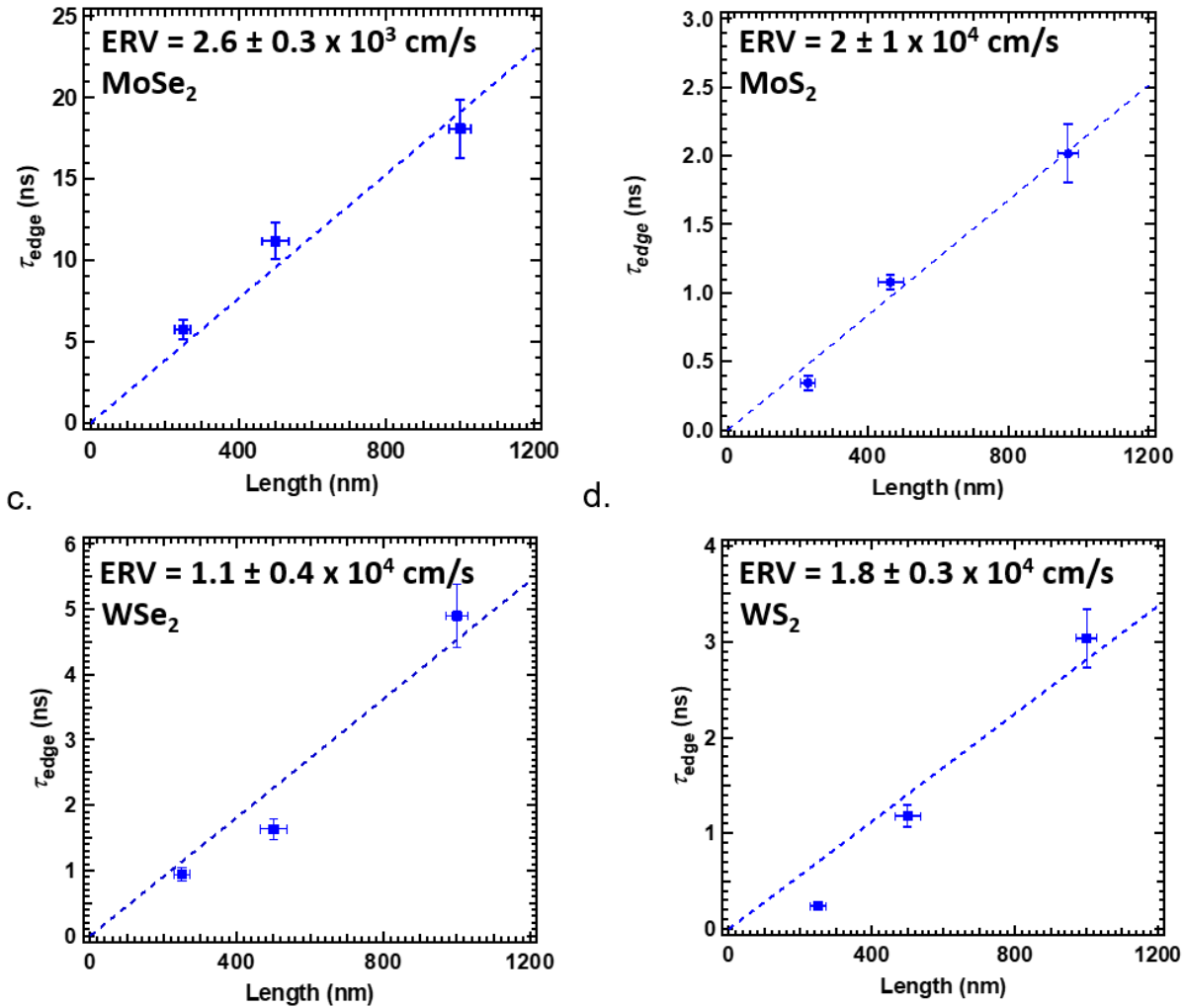
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**Figure S1.** Highspeed Data Capture of AFM sensors during the SPL process. a) Oscillation amplitude for the AFM tip - very little oscillation happens during the writing process due to the tip proximity to the sample surface (each dot took ~1 second to oxidize in this example), while the tip returns to a standard tapping mode oscillation when moving from one pixel to another. b) Tip height during a write sequence. The tip generally remains ~15 nm away from the surface when moving from pixel to pixel, while it stays very close to the surface during the actual oxidation process.

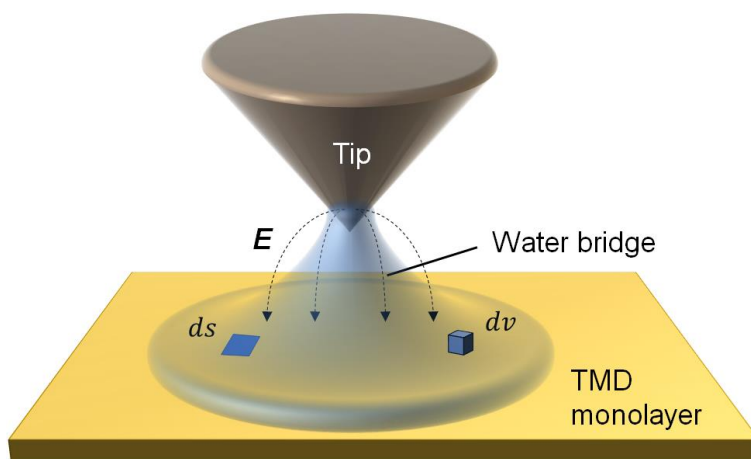


**Figure S2.** Area normalized PL spectra of all four TMDs for all 3 sizes of interest. The red spectra in each graph signifies the intensity of a control monolayer without etching. The materials are a) MoSe<sub>2</sub> b) MoS<sub>2</sub> (with TFSI) c) WSe<sub>2</sub> and d) WS<sub>2</sub> respectively.



**Figure S3.** Extracted  $\tau_{edge}$  of all four TMDs for all 3 sizes of interest. The materials are a) MoSe<sub>2</sub> b) MoS<sub>2</sub> (with TFSI) c) WSe<sub>2</sub> and d) WS<sub>2</sub> respectively. Note the significantly longer MoSe<sub>2</sub> edge lifetime reflective of its surface properties. Error bars signify the standard deviation of multiple samples of the same designed diameter.





**Figure S4.** Illustration of the tip/water interface.  $E$  is the space-varying electrical field,  $v$  represents the volume of the condensed water, and  $s$  represents the surface area of the condensed water.

## Materials Preparation and their Basic Properties

All 2D materials are purchased as bulk crystals. MoS<sub>2</sub> is purchased from SPi Supplies. All other 2D materials are purchased from HQ Graphene. The various materials are then exfoliated onto SiO<sub>2</sub>/Si substrates and monolayers mapped via optical microscope. Multilayer films are thicker than 50 nm. The used materials are all 2H variants with semiconducting properties when made into field effect transistors. The surface defect density for each of the samples was reported in our previous work.<sup>[2]</sup>

## ERV Derivation for Square Cross Sections

The methodology for finding the  $\tau_{edge}$  expression is the same as in our previous work, and the process with the appropriate square boundary condition is detailed elsewhere (Shockley's recombination velocity derivation using a germanium filament).<sup>[3, 4]</sup> In this section, we compare Shockley's analytical model directly with our approximation of the  $\tau_{edge}$  vs. ERV expression and check for percentage error. Accordingly, the exact expression for edge lifetime in relation to the recombination velocity is:

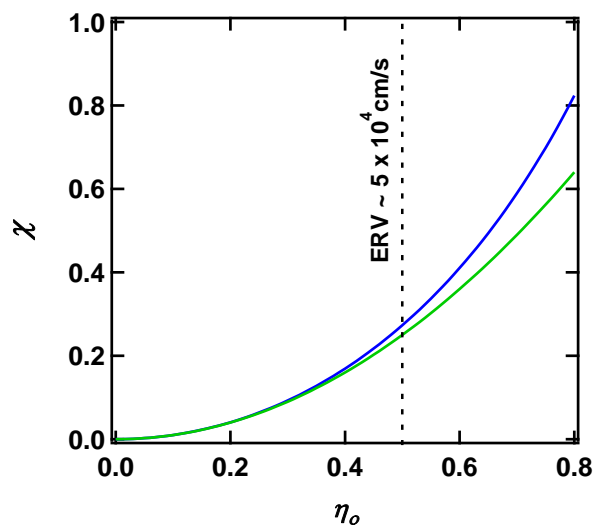
$$\frac{1}{\tau_{edge}} = 2D\left(\frac{\eta_o}{l}\right)^2 \quad (1)$$

$$\eta_o \tan(\eta_o) = \frac{ERV * l}{D} \quad (2)$$

As shown above,  $D$  is the exciton diffusion coefficient, and  $\eta_o$  is the smallest solution to the diffusion equation (yielding the longest lifetime). Equation 1 originates from applying the boundary condition of recombination velocity to all four edges of the square assuming uniform carrier distribution at  $t = 0$ . Equation 2 explicitly describes the solution's relation to ERV. Equation 1 and 2 becomes the approximation we used in the main text as:

$$\eta_o \tan(\eta_o) \rightarrow \eta_o^2 \quad (3)$$

Assuming a  $D \sim 20 \text{ cm}^2/\text{s}$  and upper limit of  $l = 1 \mu\text{m}$ , at an ERV  $\sim 5 \times 10^4 \text{ cm/s}$ , the error between the two approximation is 8.5%.<sup>[5]</sup> At lower ERVs, the error decreases and equation (4) becomes a more accurate  $\tau_{edge}$  vs ERV relation.



**Figure S5** Graphic representation of deviation error. x-axis represents either  $\eta_0^2$  (green) or  $\eta_0 \tan(\eta_0)$  (blue). At  $ERV = 5 \times 10^4$  cm/s, the error resulting from the approximation is  $\sim 8.7\%$ . Smaller ERVs will only result in smaller error, reinforcing the validity of our approximation.

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